



The existence and uniqueness of φ –Best proximity point theorems for generalized Boyd-Wong proximal contraction

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Abstract: In this paper, we study concept and expand the condition of Işık, Sezen and Vetro [11] to prove the existence and uniqueness of φ –best proximity point for (F, λ, φ) –weak proximal and (F, λ, φ) –proximal contraction. As for applications of our main results, we prove the existence and uniqueness of a fixed point on partial metric spaces and variational inequality.

Keywords: (F, λ, φ) –proximal contraction, (F, λ, φ) –weak proximal contraction, φ –best proximity point, partial metric space.

MSC: 47H10, 54H25.

1 Introduction

In 1969 Boyd and Wong [5] introduced the well-known theorems of Banach which states that, if X is a complete metric space and $T : X \rightarrow X$ satisfies $d(Tx, Ty) \leq kd(x, y)$ that constant k replaced by some control function, then T has a unique fixed point.

Now, we introduce the concept of φ –fixed point by given that (X, d) a metric space, $\varphi : X \rightarrow [0, \infty)$ and $T : X \rightarrow X$ be an operator on X . The set of all fixed points of the operator T is denoted by $F_T = \{x \in$

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$X : x = Tx$ and we said $Z_\varphi = \{x \in X : \varphi(x) = 0\}$ be the set of zeros of the function φ . The element $z \in X$ is called a φ -fixed point of the operator T if and only if $z \in F_T \cap Z_\varphi$.

In 2014 Jleli M, Samet B and Vetro C [12] introduced the idea of φ mapping and illustrated some φ -fixed point for the various classes of operators which defined on a metric space (X, d) .

Suppose (X, d) be a metric space, A, B is a nonempty subsets of X and $T : A \rightarrow B$. Then $x \in A$ is called a best proximity point of T if the followings problem,

$$d(x, Tx) = d(A, B). \tag{1.1}$$

From (1.1) if $Tx = x$ then it will be transfer to the fixed point problem.

Later then, Işık, Sezen and Vetro [11] introduced the notion of φ -best proximity point (we define in the section 2) and give two contraction include (F, φ) -proximal and weak proximal contraction prove to the existence and uniqueness of φ -best proximity point.

In this paper, we study concept and expand the condition of Işık, Sezen and Vetro [11] to prove the existence and uniqueness of φ -best proximity point by replaced constants k by a self-mapping $\lambda : [0, \infty) \rightarrow [0, \infty)$ such that $\lambda(t) < t$ for $t > 0, \lambda(0) = 0$ and $\limsup_{s \rightarrow t^+} \lambda(s) < t$ for all $t > 0$, which generalization the result. As for applications of our main results, we prove the existence and uniqueness of a fixed point on partial metric spaces and variational inequality.

2 Preliminaries and Auxiliaries

In this section, we introduce the definitions necessary to prove in section 3 as follows.

Given that (X, d) be a metric space, $T : X \rightarrow X$ be a self-mapping and $F_T = \{x \in X : Tx = x\}$ is called the set of all fixed points of T . $Z_\varphi = \{x \in X : \varphi(x) = 0\}$ when $\varphi : X \rightarrow [0, \infty)$. Moreover, \mathcal{F} , denote the collection of functions $F : [0, \infty)^3 \rightarrow [0, \infty)$ satisfying the following conditions:

- (F1) $\max\{u, v\} \leq F(u, v, w)$ for all $u, v, w \in [0, \infty)$;
- (F2) $F(u, 0, 0) = a$ for all $u \geq 0$;
- (F3) F is continuous.

Next, we will give some example of F .

- (1) $F(a, b, c) = a + b + c, \forall a, b, c \in [0, \infty)$;
- (2) $F(a, b, c) = \max\{a, b\}, \forall a, b, c \in [0, \infty)$;
- (3) $F(a, b, c) = a + b^2 + c, \forall a, b, c \in [0, \infty)$.

Next, we move to consider non-self mapping on X be let (X, d) be a metric space, A and B be nonempty subsets of X . The following notions are used in this work.

$$\begin{aligned} d(A, B) &:= \inf\{d(x, y) : x \in A, y \in B\}; \\ A_0 &:= \{x \in A : d(x, y) = d(A, B) \text{ for some } y \in B\}; \\ B_0 &:= \{y \in B : d(x, y) = d(A, B) \text{ for some } x \in A\}. \end{aligned}$$

For any non-self mapping $T : A \rightarrow B$, the set of all best proximity points of T is denoted by

$$B_{est}(T) = \{x \in A : d(x, Tx) = d(A, B)\}.$$

$Z_\varphi = \{x \in A : \varphi(x) = 0\}$ is called set of zeros of $\varphi : A \rightarrow [0, \infty)$. Next, We recommend the following important definitions.

Definition 2.1. Let $T : A \rightarrow B$ be non-self mapping, for each $x^* \in A$ if $x^* \in B_{est}(T) \cap Z_\varphi$ then x^* is said to be φ -best proximity point of T .

Definition 2.2. Let (X, d) be a metric space, A, B are nonempty subsets of X , with $F \in \mathcal{F}$, $\varphi : A \rightarrow [0, \infty)$ and $\lambda : [0, \infty) \rightarrow [0, \infty)$ be two given self-mappings such that $\lambda(t) < t$ for $t > 0$, $\lambda(0) = 0$ and $\limsup_{s \rightarrow t^+} \lambda(s) < t$ for all $t > 0$. Then, $T : A \rightarrow B$ is an (F, λ, φ) -weak proximal contraction, if there exists $M \geq 0$ such that

$$\begin{cases} d(u, Tx) = d(A, B) \\ d(v, Ty) = d(A, B) \end{cases}$$

$$\Rightarrow F(d(u, v), \varphi(u), \varphi(v)) \leq \lambda(F(d(x, y), \varphi(x), \varphi(y))) + M(F(d(y, u), \varphi(y), \varphi(u)) - F(0, \varphi(y), \varphi(u))) \quad (2.1)$$

for all $v, u, x, y \in A$

3 Main Results

In this section, we establish the existence of φ -best proximity point for (F, λ, φ) -weak proximal contraction. Afterwards, we prove the uniqueness of φ -best proximity point. By adding the assumption (H5) and using (F, λ, φ) -proximal contraction, we obtain the uniqueness of φ -best proximity point. Let (X, d) be a metric space. A and B be two nonempty subsets of X . We modify the following assumption for using in our main result.

(H1) nonempty set A_0 is complete with respect to the topology induced by d ;

(H2) $T(A_0) \subseteq B_0$;

(H3) $\varphi : A \rightarrow [0, \infty)$ is lower semi-continuous;

(H4) $T : A \rightarrow B$ is a (F, λ, φ) -weak proximal contraction.

Theorem 3.1. Assume that (H1) – (H4) hold, then there exists $x^* \in B_{est}(T)$ such that $B_{est}(T) \cap Z_\varphi$ be a nonempty set Forthermore, for any $x \in X$, the sequence $\{T^n x\}$ converges to a φ -best proximity point of T .

Proof. From (H1) and (H2), there exists element x_0 in A_0 with $Tx_0 \in T(A_0) \subseteq B_0$ we get $x_1 \in A_0$ such that $d(x_1, Tx_0) = d(A, B)$. Similarly, since $Tx_1 \in T(A_0) \subseteq B_0$. We have x_2 in A_0 such that $d(x_2, Tx_1) = d(A, B)$. Recursively the process, we obtain a sequence $\{x_n\}$ in A_0 satisfying

$$d(x_{n+1}, Tx_n) = d(A, B), \quad \forall n \in \mathbb{N}. \quad (3.1)$$

We can see that, if there exists n_0 such that $x_{n_0} = x_{n_0+1}$, then

$$d(x_{n_0}, Tx_{n_0}) = d(x_{n_0+1}, Tx_{n_0}) = d(A, B).$$

Next, we shows that x_{n_0} is a best proximity point of T and then the proof is completed. So, we suppose that $x_n \neq x_{n+1}$, for all $n \in \mathbb{N}$.

We set

$$a_n := F(d(x_n, x_{n+1}), \varphi(x_n), \varphi(x_{n+1})).$$

By (3.1),(2.1) and since $\lambda(t) < t$ for each $t > 0$, then we see that

$$\lambda(a_{n+1}) < a_{n+1} \leq \lambda(a_n) < a_n,$$

for all $n \in \mathbb{N}$. It concluded that $\{a_n\}$ and $\{\lambda(a_n)\}$ is a strictly decreasing sequence of non-negative real number and bounded below. Therefore $\lim_{n \rightarrow \infty} a_n$ exists. Assume that

$$a := \lim_{n \rightarrow \infty} a_n \geq 0.$$

We claim that $a = 0$. Suppose for the sake of contradiction that $a > 0$. If $\limsup_{s \rightarrow t^+} \lambda(s) < t, \forall t > 0$, then we obtain that $\limsup_{t_n \rightarrow a^+} \lambda(t_n) < a$ whenever $t_n \rightarrow a^+$ as $n \rightarrow +\infty$. That is

$$\begin{aligned} 0 < a &= \lim_{n \rightarrow +\infty} a_{n+1} \\ &\leq \lim_{n \rightarrow +\infty} \lambda(a_n) \\ &\leq \limsup_{s \rightarrow a^+} \lambda(s) \\ &< a, \end{aligned}$$

which is a contradiction. Thus, we must have $\lim_{n \rightarrow +\infty} a_n = 0$. Now using the condition (F1), we get

$$0 \leq \varphi(x_n) \leq \max\{d(x_n, x_{n+1}), \varphi(x_n)\} \leq F(d(x_n, x_{n+1}), \varphi(x_n), \varphi(x_{n+1})) = a_n$$

$$0 \leq d(x_n, x_{n+1}) \leq \max\{d(x_n, x_{n+1}), \varphi(x_n)\} \leq F(d(x_n, x_{n+1}), \varphi(x_n), \varphi(x_{n+1})) = a_n$$

for all $n \in \mathbb{N}$. Taking the limit as $n \rightarrow \infty$ in the above two inequalities, then we obtain

$$\lim_{n \rightarrow \infty} d(x_n, x_{n+1}) = \lim_{n \rightarrow \infty} \varphi(x_n) = 0, \text{ for each } x \in X. \quad (3.2)$$

Next, we will show that $\{x_n\}$ is a Cauchy sequence by assuming that $\{x_n\}$ is not a Cauchy sequence. Then there exists $\varepsilon > 0$ and two subsequences $\{x_{n_k}\}$ and $\{x_{m_k}\}$ of $\{x_n\}$ such that $m_k > n_k > k$ and $d(x_{m_k}, x_{n_k}) \geq \varepsilon, \forall n \in \mathbb{N}$. Then, we can choose m_k to be satisfied $d(x_{m_k-1}, x_{n_k}) < \varepsilon$. For each $k \in \mathbb{N}$, we obtain

$$\begin{aligned} \varepsilon &\leq d(x_{m_k}, x_{n_k}) \\ &\leq d(x_{m_k}, x_{m_k-1}) + d(x_{m_k-1}, x_{n_k}) \\ &\leq d(x_{m_k}, x_{m_k-1}) + \varepsilon \end{aligned}$$

we have

$$\lim_{k \rightarrow \infty} d(x_{m_k}, x_{n_k}) = \varepsilon. \quad (3.3)$$

By using (3.2),(3.3),(F2) and the continuity of F , we will get

$$\lim_{k \rightarrow \infty} F(d(x_{m_k}, x_{n_k}), \varphi(x_{m_k}), \varphi(x_{n_k})) = F(\varepsilon, 0, 0) = \varepsilon. \quad (3.4)$$

Then by using the contractive condition (2.1), (F1) and the triangle inequality, we obtain, $\forall k \in \mathbb{N}$:

$$\begin{aligned} d(x_{m_k}, x_{n_k}) &\leq d(x_{m_k}, x_{m_{k+1}}) + d(x_{m_{k+1}}, x_{n_{k+1}}) + d(x_{n_{k+1}}, x_{n_k}) \\ &\leq d(x_{m_k}, x_{m_{k+1}}) + \max\{d(x_{m_{k+1}}, x_{n_{k+1}}) + \varphi(x_{m_{k+1}})\} + d(x_{n_{k+1}}, x_{n_k}) \\ &\leq d(x_{m_k}, x_{m_{k+1}}) + F(d(x_{m_{k+1}}, x_{n_{k+1}}), \varphi(x_{m_{k+1}}), \varphi(x_{n_{k+1}})) + d(x_{n_{k+1}}, x_{n_k}) \\ &\leq d(x_{m_k}, x_{m_{k+1}}) + \lambda(F(d(x_{m_k}, x_{n_k}), \varphi(x_{m_k}), \varphi(x_{n_k}))) + d(x_{n_{k+1}}, x_{n_k}). \end{aligned}$$

For all $k \in \mathbb{N}$. Taking $k \rightarrow \infty$ in the above inequality, using (3.2), (3.4), $\limsup_{s \rightarrow t^+} \lambda(s) < t, \forall t > 0$ and the continuity of F and $F_k := F(d(x_{m_k}, x_{n_k}), \varphi(x_{m_k}), \varphi(x_{n_k}))$ with $\lim_{k \rightarrow \infty} F_k = \varepsilon$, we get

$$\begin{aligned} \varepsilon &= \lim_{k \rightarrow \infty} d(x_{m_k}, x_{n_k}) \\ &\leq \limsup_{k \rightarrow \infty} \lambda(F(d(x_{m_k}, x_{n_k}), \varphi(x_{m_k}), \varphi(x_{n_k}))) \\ &= \limsup_{k \rightarrow \infty} \lambda(F_k) \\ &\leq \limsup_{s \rightarrow \varepsilon^+} \lambda(s) \\ &< \varepsilon \end{aligned}$$

which is a contradiction. Then $\{x_n\}$ is a Cauchy sequence in X . Since A_0 is complete, there exists $x^* \in A_0$ such that

$$\lim_{n \rightarrow \infty} d(x_n, x^*) = 0. \quad (3.5)$$

Now, we show that x^* is a φ -best proximity point of T . By (3.2), (3.5) and φ is lower semi-continuous, we will get

$$\varphi(x^*) = 0. \quad (3.6)$$

And, since $x^* \in A_0$. By using (H2), we have $z \in A_0$ such that

$$d(z, Tx^*) = d(A, B). \quad (3.7)$$

By (H4), (3.1), (3.7) we obtain

$$\begin{aligned} F(d(x_{n+1}, z), \varphi(x_{n+1}), \varphi(z)) &\leq \lambda(F(d(x_n, x^*), \varphi(x_n), \varphi(x^*))) + M[F(d(x_{n+1}, x^*), \varphi(x_{n+1}), \varphi(x^*)) \\ &\quad - F(0, \varphi(x_{n+1}), \varphi(x^*))]. \end{aligned}$$

Taking the limit as $n \rightarrow \infty$ and use (3.5), (3.2), (3.6) and the continuity of F , we have

$$F(d(x^*, z), 0, \varphi(z)) \leq \lambda(F(0, 0, 0)).$$

By (F2), we get

$$F(d(x^*, z), 0, \varphi(z)) \leq 0.$$

From condition (F1), we obtain $d(x^*, z) = 0$ and so $x^* = z$. By (3.7), we have

$$d(x^*, Tx^*) = d(A, B).$$

Imply that x^* is a φ -best proximity point of T . □

Example 3.2. Let $X = [0, 1] \cup \{2, 3, 4, \dots\}$ and $d : X \times X \rightarrow \mathbb{R}$ be defined by $d((x, i), (y, j)) = \sqrt{d_x^2(x, y) + |i - j|^2}$ when

$$d_x(x, y) = \begin{cases} |x - y| & , \text{ if } x, y \in [0, 1] \\ x + y & , \text{ if } x \text{ or } y \notin [0, 1], x \neq y \\ 0 & , \text{ if } x \text{ or } y \notin [0, 1], x = y. \end{cases}$$

Let $A = X \times \{0\} = A_0$, $B = X \times \{1\} = B_0$ and $d(A, B) = 1$. Let $F : [0, \infty)^3 \rightarrow [0, \infty)$ defined by $F(a, b, c) = a + b$, $T : A \rightarrow B$ be defined by

$$T(x, 0) = \begin{cases} (x - \frac{1}{2}x^2, 1) & , x, y \in [0, 1] \\ (x - 1, 1) & , x \notin [0, 1] \end{cases}$$

and $\lambda : X \rightarrow [0, \infty)$ defined by

$$\lambda(t) = \begin{cases} t - \frac{1}{2}t^2 & , t \in [0, 1] \\ t - 1 & , t > 1. \end{cases}$$

Finally, defined

$$\varphi(x) = \begin{cases} 1_{X \cap [2, \infty)} \\ 0_{x \in [0, 1]} \end{cases}$$

Proof. We set $M = 1$

Case 1 If $x, y \in [0, 1] \Rightarrow u, v \in [0, 1]$

$$\begin{aligned} F(d(u, v), \varphi(u), \varphi(v)) &= d\left(\left(x - \frac{1}{2}x^2, 0\right), \left(y - \frac{1}{2}y^2, 0\right)\right) \\ &= \left|x - \frac{1}{2}x^2 - \left(y - \frac{1}{2}y^2\right)\right| \end{aligned}$$

$$\begin{aligned} \lambda(F(d(x, y), \varphi(x), \varphi(y))) + d(y, Tx) &= \lambda(d((x, 0), (y, 0))) + d((y, 0), (x - \frac{1}{2}x^2, 1)) \\ &= \lambda(|x - y|) + \sqrt{(y - x + \frac{1}{2}x^2) + 1} \\ &= \left(|x - y| - \frac{1}{2}(x - y)^2\right) + \sqrt{(y - x + \frac{1}{2}x^2) + 1}. \end{aligned}$$

$$\text{Hence } \left(x - \frac{1}{2}x^2\right) - \left(y - \frac{1}{2}y^2\right) \leq \left(|x - y| - \frac{1}{2}(x - y)^2\right) + \sqrt{(y - x + \frac{1}{2}x^2) + 1}.$$

Case 2 If $x, y \notin [0, 1], x \neq y$

If $x = (2, 0)$ then $y > 2$, we will get

$$\begin{aligned} F(d(u, v), \varphi(u), \varphi(v)) &= d((1, 0), (y - 1, 0)) \\ &= \sqrt{(1 + y - 1)^2 + 0} = \sqrt{y^2} = y \\ \text{and } F(d(u, v), \varphi(v), \varphi(u)) &= d((1, 0), (y - 1, 0)) + 1 \\ &= \sqrt{(1 + y - 1)^2 + 0} + 1 = y + 1 \end{aligned}$$

$$\begin{aligned} \lambda(F(d(x, y), \varphi(x), \varphi(y))) + d(y, Tx) &= \lambda(d((2, 0), (y, 0)) + 1) + d((y, 0), (1, 1)) \\ &= \lambda(y + 3) + \sqrt{(y + 1)^2 + 1} \\ &= (y + 2) + \sqrt{(y + 1)^2 + 1}. \end{aligned}$$

Hence $y + 1 < (y + 2) + \sqrt{(y + 1)^2 + 1}$.

If $x \neq y \neq (2, 0)$

$$\begin{aligned} F(d(u, v), \varphi(u), \varphi(v)) &= d((x - 1, 0), (y - 1, 0)) + 1 \\ &= x + y - 1 \end{aligned}$$

$$\begin{aligned} \lambda(F(d(x, y), \varphi(x), \varphi(y))) + d(y, Tx) &= \lambda(d((x, 0), (y, 0)) + 1) + d((y, 0), (x - 1, 1)) \\ &= \lambda(x + y + 1) + \sqrt{(x + y - 1)^2 + 1} \\ &= (x + y) + \sqrt{(x + y - 1)^2 + 1}. \end{aligned}$$

Hence $(x + y - 1) \leq (x + y) + \sqrt{(x + y - 1)^2 + 1}$.

Case 3 If $x \in [0, 1]$, $y \notin [0, 1]$

If $y = (2, 0)$, we get

$$\begin{aligned} F(d(u, v), \varphi(u), \varphi(v)) &= d((x - \frac{1}{2}x^2, 0), (1, 0)) \\ &= (x + 1 - \frac{1}{2}x^2) \end{aligned}$$

$$\begin{aligned} \lambda(F(d(x, y), \varphi(x), \varphi(y))) + d(y, Tx) &= \lambda(d((x, 0), (2, 0))) + d((2, 0), (x - \frac{1}{2}x^2, 1)) \\ &= \lambda(x + 2) + \sqrt{(2 + x - \frac{1}{2}x^2)^2 + 1} \\ &= (x + y) + \sqrt{(2 + x - \frac{1}{2}x^2)^2 + 1}. \end{aligned}$$

If $y > (2, 0)$, we get

$$\begin{aligned} F(d(u, v), \varphi(u), \varphi(v)) &= d((x - 1, 0), (y - 1, 0)) + 1 \\ &= x + y - 1 \end{aligned}$$

$$\begin{aligned}
 \lambda(F(d(x, y), \varphi(x), \varphi(y))) + d(y, Tx) &= \lambda(d((x - \frac{1}{2}x^2, 0), (y - 1, 0))) + d((y, 0), (x - \frac{1}{2}x^2, 1)) \\
 &= \lambda(x + y) + \sqrt{(y + x - \frac{1}{2}x^2)^2 + 1} \\
 &= (x + y - 1) + \sqrt{(y + x - \frac{1}{2}x^2)^2 + 1} \\
 \text{and } \lambda(F(d(x, y), \varphi(y), \varphi(x))) + d(y, Tx) &= (x + y) + \sqrt{(y + x - \frac{1}{2}x^2)^2 + 1}.
 \end{aligned}$$

□

Next, we can prove uniqueness of theorem 3.1 by similar establishing to the case of an (F, λ, φ) -weak proximal contraction.

(H5) There exist $M \geq 0$ such that

$$\begin{cases} d(u, Tx) = d(A, B) \\ d(v, Ty) = d(A, B) \end{cases}$$

$$\Rightarrow F(d(u, v), \varphi(u), \varphi(v)) \leq \lambda(F(d(x, y), \varphi(x), \varphi(y))) + M(F(d(x, u), \varphi(x), \varphi(u)) - F(0, \varphi(x), \varphi(u))) \quad (3.8)$$

$\forall u, v, x, y \in A$

Theorem 3.3. Suppose that (H1) – (H5) hold, then there exists $x^* \in A$ is a unique solution such that $B_{est}(T) \cap Z_\varphi = \{x^*\}$. Furthermore, for any $x \in X$ we have $\lim_{n \rightarrow \infty} T^n x = x^*$.

Proof. We prove the uniqueness of φ -best proximity point. From theorem 3.1, there exists x^* be a φ -best proximity point of T . Assume that ζ is also φ -best proximity point of T , then we have

$$d(x^*, Tx^*) = d(\zeta, T\zeta) = d(A, B), \quad \varphi(x^*) = 0, \quad \text{and} \quad \varphi(\zeta) = 0.$$

By (H5), we get

$$\begin{aligned}
 F(d(x^*, \zeta), \varphi(x^*), \varphi(\zeta)) &\leq \lambda(F(d(x^*, \zeta), \varphi(x^*), \varphi(\zeta))) \\
 &\quad + M[F(d(x^*, x^*), \varphi(x^*), \varphi(x^*)) - F(0, \varphi(x^*), \varphi(x^*))] \\
 &= \lambda(F(d(x^*, \zeta), \varphi(x^*), \varphi(\zeta))) \\
 \Rightarrow F(d(x^*, \zeta), 0, 0) &\leq \lambda(F(d(x^*, \zeta), 0, 0)).
 \end{aligned}$$

We conclude that $d(x^*, \zeta) = 0$ which means that $x^* = \zeta$. Hence, x^* is a unique φ -best proximity point of T . □

Next results $M = 0$ then our contraction reduce to (F, λ, φ) -proximal as follows:

Definition 3.4. Let (X, d) be a metric space, A and B be two nonempty subsets of X with $F \in \mathcal{F}$, $\varphi : A \rightarrow [0, \infty)$ and $\lambda : [0, \infty) \rightarrow [0, \infty)$ be two given funtions such that $\lambda(t) < t$ for $t > 0$, $\lambda(0) = 0$ and $\limsup_{s \rightarrow t^+} \lambda(s) < t$ for all $t > 0$. Then, $T : A \rightarrow B$ is an (F, λ, φ) -proximal contraction, if

$$\begin{cases} d(u, Tx) = d(A, B) \\ d(v, Ty) = d(A, B) \end{cases} \Rightarrow F(d(u, v), \varphi(u), \varphi(v)) \leq \lambda(F(d(x, y), \varphi(x), \varphi(y))) \quad (3.9)$$

for all $u, v, x, y \in A$

Theorem 3.5. *Suppose that (H1) – (H3) and (3.4) hold, then there exists $x^* \in A$ is a unique solution such that $B_{est}(T) \cap Z_\varphi = \{x^*\}$. Furthermore, for any $x \in X$ then we have $\lim_{n \rightarrow \infty} T^n x = x^*$.*

Proof. From Theorem 3.1, denote by $M = 0$, we have x^* is a φ –best proximity point of T . Now, we show that $B_{est}(T) \cap Z_\varphi$ is a singleton. Assume that $\zeta \in A$ is another φ –best proximity point of T , so, we have

$$d(x^*, Tx^*) = d(\zeta, T\zeta) = d(A, B), \quad \varphi(x^*) = 0, \quad \text{and} \quad \varphi(\zeta) = 0.$$

From (3.9) we obtain

$$F(d(x^*, \zeta), \varphi(x^*), \varphi(\zeta)) \leq \lambda(F(d(x^*, \zeta), \varphi(x^*), \varphi(\zeta))).$$

$$\text{Then, we have } F(d(x^*, \zeta), 0, 0) \leq \lambda(F(d(x^*, \zeta), 0, 0)),$$

which implies that $d(x^*, \zeta) = 0$, so we get $x^* = \zeta$. Therefore, x^* is a unique φ –best proximity point of T . □

4 Applications

In this section, we prove result in partial metric space and variational inequality problem by theorem 3.1

4.1 Some consequences on partial metric space

Definition 4.1. Matthews [15]. A partial metric on a nonempty set X is a function $p : X \times X \rightarrow [0, \infty)$ such that for all $x, y, z \in X$:

$$(P1) \quad x = y \Leftrightarrow p(x, x) = p(x, y) = p(y, y);$$

$$(P2) \quad p(x, x) \leq p(x, y);$$

$$(P3) \quad p(x, y) = p(y, x);$$

$$(P4) \quad p(x, y) \leq p(x, z) + p(z, y) - p(z, z).$$

A partial metric space is a pair (X, p) such that X is a nonempty set and p is a partial metric on X .

From (P1) and (P2) $x = y$, if $p(x, y) = 0$, But conversely is not true. see again Matthews [15].

Notice that every partial metric on X generates a T_0 topology τ_p on X , which has as a base the family of open p –balls $\{B_p(x, \varepsilon) : x \in X, \varepsilon > 0\}$, where $B_p(x, \varepsilon) = \{y \in X : p(x, y) < p(x, x) + \varepsilon\}$, for each $x \in X$ and $\varepsilon > 0$. If p is a partial metric on X , then the function $d_p : X \times X \rightarrow [0, \infty)$ define by

$$d_p(x, y) = 2p(x, y) - p(x, x) - p(y, y)$$

which is a metric on X . And

$$\lim_{n \rightarrow \infty} d_p(x_n, x) = 0 \Leftrightarrow p(x, x) = \lim_{n \rightarrow +\infty} p(x_n, x) = \lim_{m, n \rightarrow +\infty} p(x_n, x_m).$$

Next, suppose that (X, p) be a partial metric space. Then,

- (I) a sequences $\{x_n\} \in (X, p)$ converges to $x \in X$ if and only if $p(x, x) = \lim_{n \rightarrow \infty} p(x_n, x)$;
- (II) We said that a sequences $\{x_n\}$ in (X, p) is a Cauchy sequence if there exists (and is finite) $\lim_{m, n \rightarrow \infty} p(x_n, x_m)$;
- (III) If every Cauchy sequence $\{x_n\} \in X$ converges with respect to τ_p to a point $x \in X$, that is $p(x, x) = \lim_{m, n \rightarrow \infty} p(x_n, x_m)$, then (X, p) is said to complete.

Next, we show the following lemmas. Which represent the connect of Cauchyness and Completeness in (X, p) and (X, d_p) .

Lemma 4.2. [15] Suppose (X, p) be a partial metric space. Let $\{x_n\}$ be any sequence in X . Then,

- (i) $\{x_n\}$ is a Cauchy sequence in (X, p) if and only if it is a Cauchy sequence in the metric space (X, d_p) ;
- (ii) (X, p) is called a complete if and only if the metric space (X, d_p) is complete.

Lemma 4.3. [16] Suppose (X, p) be a partial metric space and $\varphi : X \rightarrow [0, \infty)$ defined by $\varphi(x) = p(x, x)$. Then the function φ is lower semi-continuous in the metric space (X, d_p) .

Now, Suppose that (X, p) be a partial metric space. A and B be nonempty subset of X . By considering a non-self mapping $T : A \rightarrow B$. Then,

$$\begin{aligned} p(A, B) &:= \inf\{p(x, y) : x \in A, y \in B\}; \\ A_0 &:= \{x \in A : p(x, y) = p(A, B) \text{ for some } y \in B\}; \\ B_0 &:= \{y \in B : p(x, y) = p(A, B) \text{ for some } x \in A\}. \end{aligned}$$

Furthermore, we will see the best proximity point problem as follow.

$$\text{Find } x \in A \text{ such that } p(x, Tx) = p(A, B). \tag{4.1}$$

And let hypotheses it the followings:

- ($\overline{H1}$) nonempty set A_0 is complete with respect to the topology induced by p ;
- ($\overline{H2}$) $T(A_0) \subseteq B_0$;
- ($\overline{H3}$) there exists $\lambda : [0, \infty) \rightarrow [0, \infty)$ be given mappings such that $\lambda(t) < t$ for $t > 0$, $\lambda(0) = 0$ and

$\limsup_{s \rightarrow t^+} \lambda(s) < t$ for all $t > 0$. Such that

$$\begin{cases} p(u, Tx) = p(A, B) \\ p(v, Ty) = p(A, B) \end{cases} \Rightarrow p(u, v) \leq \lambda(p(x, y))$$

for all $u, v, x, y \in A$;

($\overline{H4}$) there exists $\lambda : [0, \infty) \rightarrow [0, \infty)$ and $M \geq 0$ such that

$$\begin{cases} p(u, Tx) = p(A, B) \\ p(v, Ty) = p(A, B) \end{cases} \Rightarrow p(u, v) \leq \lambda(p(x, y)) + M \left(p(y, u) - \frac{p(y, y) + p(u, u)}{2} \right)$$

for all $u, v, x, y \in A$;

($\overline{H5}$) there exists $\lambda : [0, \infty) \rightarrow [0, \infty)$ and $M \geq 0$ such that

$$\begin{cases} p(u, Tx) = p(A, B) \\ p(v, Ty) = p(A, B) \end{cases} \Rightarrow p(u, v) \leq \lambda(p(x, y)) + M \left(p(x, u) - \frac{p(y, y) + p(u, u)}{2} \right)$$

for all $u, v, x, y \in A$;

Corollary 4.4. Suppose that ($\overline{H1}$) – ($\overline{H3}$) hold, then problem (4.1) admits a unique solution.

Proof. Let metric d_p defined by $d_p(x, y) = 2p(x, y) - p(x, x) - p(y, y) \forall x, y \in X$ and $\varphi : X \rightarrow [0, \infty)$ defined by $\varphi(x) = p(x, x)$. Then we immediately obtain the consequence that

$$p(x, y) = \frac{d_p(x, y) + p(x, x) + p(y, y)}{2}.$$

Therefore, the inequality $p(u, v) \leq \lambda(p(x, y))$ leads to

$$d_p(u, v) + \varphi(u) + \varphi(v) \leq \lambda(d_p(x, y) + \varphi(x) + \varphi(y)).$$

Next, by Theorem 3.5 and $F(a, b, c) = a + b + c$, $d = d_p$, then we will get the following results. □

Corollary 4.5. Suppose that ($\overline{H1}$), ($\overline{H2}$) and ($\overline{H4}$) hold, then problem (4.1) admits at least a solution.

Corollary 4.6. Suppose that ($\overline{H1}$), ($\overline{H2}$), ($\overline{H4}$) and ($\overline{H5}$) hold, then problem (4.1) admits a unique solution.

4.2 A variational inequality problem

Let H be a real Hilbert space, with inner product $\langle \cdot, \cdot \rangle$ and induced norm $\| \cdot \|$. Let $K \neq \emptyset$ closed and convex subset of H and operator $S : H \rightarrow H$. Consider variational inequality problem:

$$\text{Find } u \in K \text{ such that } \langle Su, v - u \rangle \geq 0, \forall v \in K. \tag{4.2}$$

Suppose that $P_K : H \rightarrow K$; is a metric projection operator. Then,

$$\|u - P_K u\| \leq \|u - v\|, \forall v \in K \text{ holds true.}$$

Lemma 4.7. For every $z \in H$, $u \in K$ satisfies $\langle u - z, y - u \rangle \geq 0, \forall y \in K$ if and only if $u = P_K z$.

Lemma 4.8. Suppose that $S : H \rightarrow H$ be a mapping on H . Then, $u \in K$ is a solution of $\langle Su, v - u \rangle \geq 0, \forall v \in K$, if and only if $u = P_K(u - \lambda Su)$, with $\lambda > 0$.

Let $F_{ix}(S) = \{u \in H : u = Su\}$. We recommend the following important hypotheses:

(V1) $\varphi : K \rightarrow [0, \infty)$ is lower semi-continuous, with $Z_\varphi = \{u \in K : \varphi(u) = 0\}$;

(V2) $P_K(I_K - \lambda S) : K \rightarrow K$, with $\lambda > 0$, is an

(i) (F, λ, φ) -proximal contraction;

(ii) (F, λ, φ) -weak proximal contraction

Theorem 4.9. *Assume that (V1), (V2)(i) hold, then problem (4.2) admits a unique solution $u^* \in K$ such that $F_{ix}(P_K(I_K - \lambda S)) \cap Z_\varphi = \{u^*\}$. Moreover, for each $u_0 \in K$, there exists a sequence $\{u_n\} \subseteq K$ such that $u_{n+1} = P_K(u_n - \lambda S u_n)$ for every $n \in \mathbb{N} \cup \{0\}$ and $\lim_{n \rightarrow \infty} u_n = u^*$.*

Proof. Let operator $T : K \rightarrow K$ defined by $Tx = P_K(x - \lambda Sx)$, for all $x \in K$ if and only if $u^* = Tu^*$. Suppose that $A = B = K$ and T satisfies the hypotheses of Theorem 3.5, then we have the fixed point problem $u = Tu$ admits a unique solution $u^* \in K$. \square

Next, we obtain a theorem that produce at least one solution.

Theorem 4.10. *Assume that (V1), (V2)(ii) hold, then problem (4.2) admits at least a solution such that $F_{ix}(P_K(I_K - \lambda S)) \cap Z_\varphi \neq \emptyset$. Moreover, for each $u_0 \in K$, there exists $\{u_n\} \subseteq K$ such that $u_{n+1} = P_K(u_n - \lambda S u_n)$ for each $n \in \mathbb{N} \cup \{0\}$ and $\lim_{n \rightarrow \infty} u_n = u^* \in F_{ix}(P_K(I_K - \lambda S)) \cap Z$.*

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